



Thermal Model Development for an X-Ray Mirror Assembly

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Overview



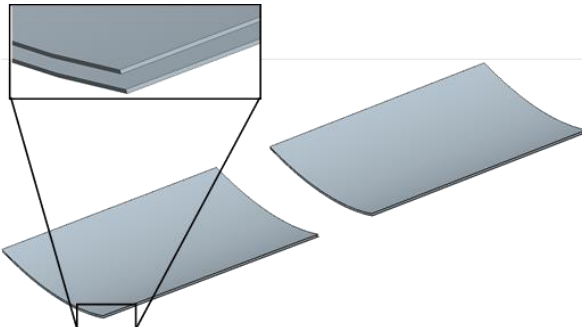
- **Purpose:** Present innovations and techniques developed to overcome challenges in the thermal modeling of the mirror assembly for a future space-based x-ray telescope.
- **Outline**
 - **Introduction:** X-Ray Optics And Their Thermal Challenges
 - **Topic 1:** Rapidly Create and Edit Large Number Of Similar Thermal Desktop Solids
 - **Topic 2:** Creating Complex Geometry From Merged Thermal Desktop Solids
 - **Topic 3:** Use SINDA Solver To Determine Optimal Heater Set Points
 - **Conclusion:** Initial STOP Analysis Results

Brief Introduction To X-Ray Optics



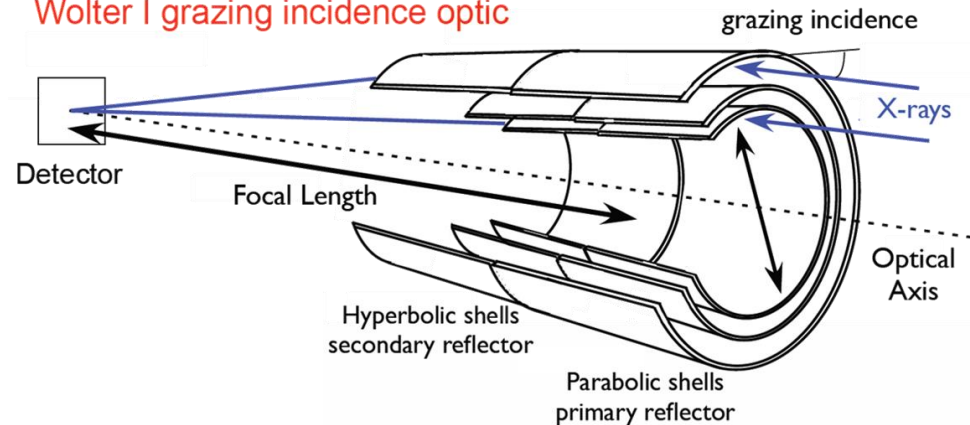
- X-Rays Focused Using Grazing-Incidence Optics
 - Grazing Reflection Efficiency Depends on X-Ray Energy
 - High Incidence Soft X-Rays (~ 1 keV) will be Absorbed by Most Materials
- Future Optics Use Hundreds of Thin, Concentric Shells to Increase Effective Area
 - Each Shell Includes Primary and Secondary Mirror Pair
 - 160 m^2 Actual Mirror Area Required for 1 m^2 Effective Collecting Area @ 1keV
- Focusing Goal, Point Spread Function (PSF): 5 arc-second half-power diameter
- Allocated Thermal Distortion PSF: ~ 1 arc-second half-power diameter

Mirror Segment Pairs and Packing



2/19/2013

Wolter I grazing incidence optic

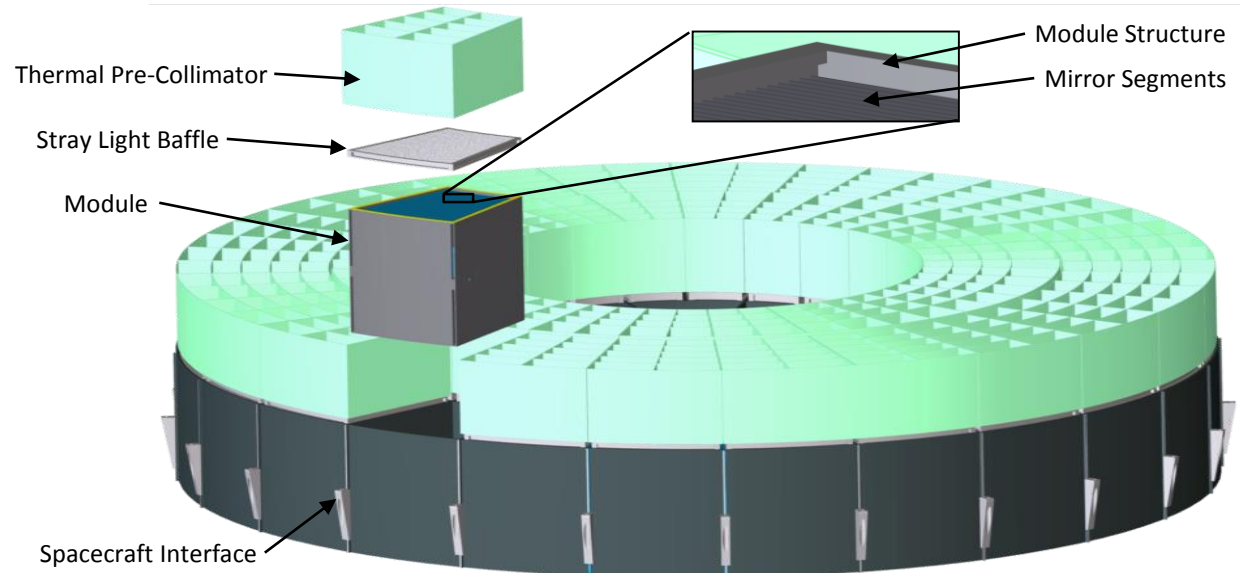
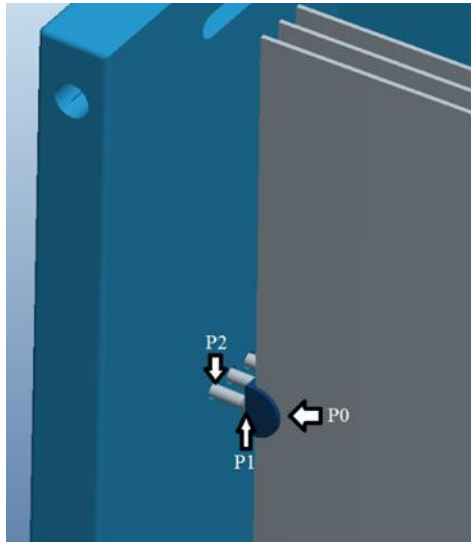


Delivery Excellence Program
SGT Proprietary Information

Future X-Ray Mirror Assembly



- Practical Application: Shells Divided into Segments, Mounted in Modules, and Secured in Structure
 - 135 Shells Grouped In 3 Structural Rings: 59 inner, 40 middle, 36 outer shells
 - Rings Divided Into Modules: 18 inner, 30 middle, 36 outer modules per ring
 - 7,116 Mirror Segments Total (3558 Mirror Segment Pairs)



Thermal Challenges for Future X-Ray Mirror Assembly



- Tightly Control Mirror Segments and Modules Near 20 °C to Minimize Distortion
 - Differential Thermal Expansion Distorts Mirror Segments or Changes Focus
 - Heat Flow via Pins Creates Axial Temperature “Waviness” in Mirror Segments
- Thermal Control of Mirror Assembly Complicated
 - Open to Large View Factor of Cold Space at Front
 - Open to Smaller View Factor of Cold Focal Plane at Back
- Thermal Solutions:
 - Surround Mirror Assembly with Heated Structure While Minimally (or Acceptably) Impacting PSF from Introduced Stray Light Reflections
 - Heated Stray-Light Baffles and Pre-Collimators in Front (Stray Light Impact)
 - Heated Structure on Sides (No Stray Light Impact)
 - High Thermal Conductivity for Mirror Segments and Module Structure
 - Low Thermal Conductivity for Pins
 - Best Match Thermal Expansion Coefficient for Pins, Mirrors, and Module Structure
 - Low IR Emissivity for Mirror Segments, High IR Emissivity for Structure
- **Detailed Thermal Modeling Together With Structural-Optical-Thermal (STOP) Analysis Required To Verify Design Choices.**

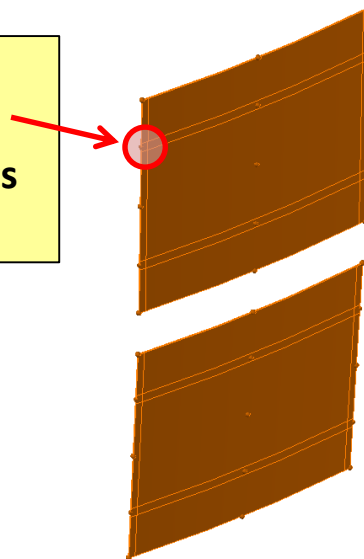
Topic 1: Method to Rapidly Build Mirror Segments for Thermal Model



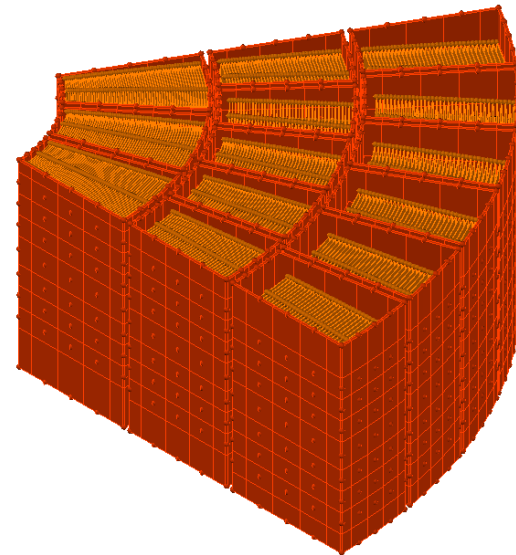
- Thermal Desktop Model of Mirror Assembly with Sufficient Detail for STOP Analysis Requires Building Large Number of Mirror Segments.
- Issue: How to Build Thousands of Mirror Segments and Modify Them as Needed with Minimum Man-Hours?
- **Solution: Parameterize with Thermal Desktop Symbols and Develop Tools to Create and Import the Thousands of Symbols Required.**

Model for Mirror Segment Pair:

Small Nodal Area Models
Contact Area of Clip for
Mounting Mirror Segments
(4 Places Per Segment)



60-Degree Wedge of Mirror Segments in Modules:



Topic 1: Building Mirror Segments, Creating and Importing TD Symbols

- Step #1: Create and Import Thermal Desktop Symbols that Parameterize Mirrors
 - Prescription Data: Height, Top Radius, Base Radius, Axial Position, (Thickness)
 - Additional Parameters: Azimuthal Angle, Density Factor
 - Used 2160 Symbols (8 each for Primary and Secondary Segments in 135 Shells)
 - Use 4-Character Suffix to Identify Mirror Segment: ***_{P/S}{nnn}***

STARX_Symbols_Rev31.xlsm - Microsoft Excel

FileHomeInsertPage LayoutFormulasDataReviewViewDeveloperAutodesk Vault

PasteCutCopyFormat PainterClipboard

Calibri11A⁺_−
B I U Font

Merge & Center Alignment

General\$ % Number

Conditional FormattingFormat as TableNormalBadGoodNeutralCalculationCheck CellStyles

InsertDeleteFormatCells

AutoSumFillClearEditing

Sort & FilterFind & Select

D12 [=Rx_TopR_Prims]

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	
2			Calculated by VBA	INPUT THESE COLUMNS					Calculated	INPUT THESE COLUMNS				Calculated by Excel Formula			
3				COPY AND PASTE THESE COLUMNS INTO THE .SYM TEXT FILE													
	Symbol Count	Calculate Before Add Name	Evaluated Expression	Note: All unempty rows must have a valid TD Symbol Name and Excel Name or the macro will bomb.	Note: If Text Expression is blank, the Evaluated Expression in column C will be "".	Comment	Note: If blank, TD imports symbol into group "general".	Note: If blank, TD uses 0000.	Output as SINDA Register: On, Off Default: blank	Expression, Value Default: Val	Type: Double, Integer Default: blank	Check Units: On, Off Default: On	Output as SINDA Register	Exp or Val	Double or Integer	Check Consist. Units	
4		Calculate	Excel	TD Symbol Name (also Excel Name)	TD Symbol Text Expression		Symbol Group Name	Binary									
6	1		0.4	Rx_MirrorThick		0.400 [mm]	1_Rx	0001		Val		On	0	0	0	1	
7	2		15	Rx_CordDistBetweenSegments	FMA_Primary_SpokeThick + 2*(FMA_Gap_PrimarytoModuleSpoke + FMA_Module_Spo	[mm]	1_Rx	0001		Val		On	0	0	0	1	
8	3		4	Rx_Clip_SeatOD	4.000000	[mm]	1_Rx	0001		Val		On	0	0	0	1	
9	4		0.25	Rx_Clip_SeatExtL	0.250000	[mm]	1_Rx	0001		Val		On	0	0	0	1	
10	5		1.0414	Rx_Pin_ShaftOD	1.041400	[mm]	1_Rx	0001		Val		On	0	0	0	1	
11	6		105	Rx_TopR_Prims_000	1.050000E+02	[mm] Unedited object value	1_Rx	0001		Val		On	0	0	0	1	
12	7		175.5684	Rx_TopR_Prims_148	1.755684E+02	[mm]	1_Rx	0001		Val		On	0	0	0	1	
13	8		177.7615	Rx_TopR_Prims_147	1.777615E+02	[mm]	1_Rx	0001		Val		On	0	0	0	1	
14	9		179.9657	Rx_TopR_Prims_146	1.799657E+02	[mm]	1_Rx	0001		Val		On	0	0	0	1	
15	10		182.181	Rx_TopR_Prims_145	1.821810E+02	[mm]	1_Rx	0001		Val		On	0	0	0	1	
16	11		184.4074	Rx_TopR_Prims_144	1.844074E+02	[mm]	1_Rx	0001		Val		On	0	0	0	1	
2686	2681		1.00391174	Rx_DensFact_Sec_007	1.003912E+00	[degr]	1_Rx	0001		Val		On	0	0	0	1	
2687	2682		1.00387952	Rx_DensFact_Sec_006	1.0038800E+00	[degr]	1_Rx	0001		Val		On	0	0	0	1	
2688	2683		1.00384767	Rx_DensFact_Sec_005	1.0038488E+00	[degr]	1_Rx	0001		Val		On	0	0	0	1	
2689	2684		1.00381618	Rx_DensFact_Sec_004	1.0038166E+00	[degr]	1_Rx	0001		Val		On	0	0	0	1	
2690	2685		1.00378505	Rx_DensFact_Sec_003	1.0037855E+00	[degr]	1_Rx	0001		Val		On	0	0	0	1	
2691	2686		1.00375427	Rx_DensFact_Sec_002	1.0037544E+00	[degr]	1_Rx	0001		Val		On	0	0	0	1	
2692	2687		1.00372384	Rx_DensFact_Sec_001	1.0037246E+00	[degr]	1_Rx	0001		Val		On	0	0	0	1	

Rx SymbolsSLB SymbolsFMA SymbolsPCL SymbolsSPC SymbolsGMM and Node IndexConductor IndexRx and SLB DataRx Subdivision ListsRx Raw DataRx Max and Min R

FMA

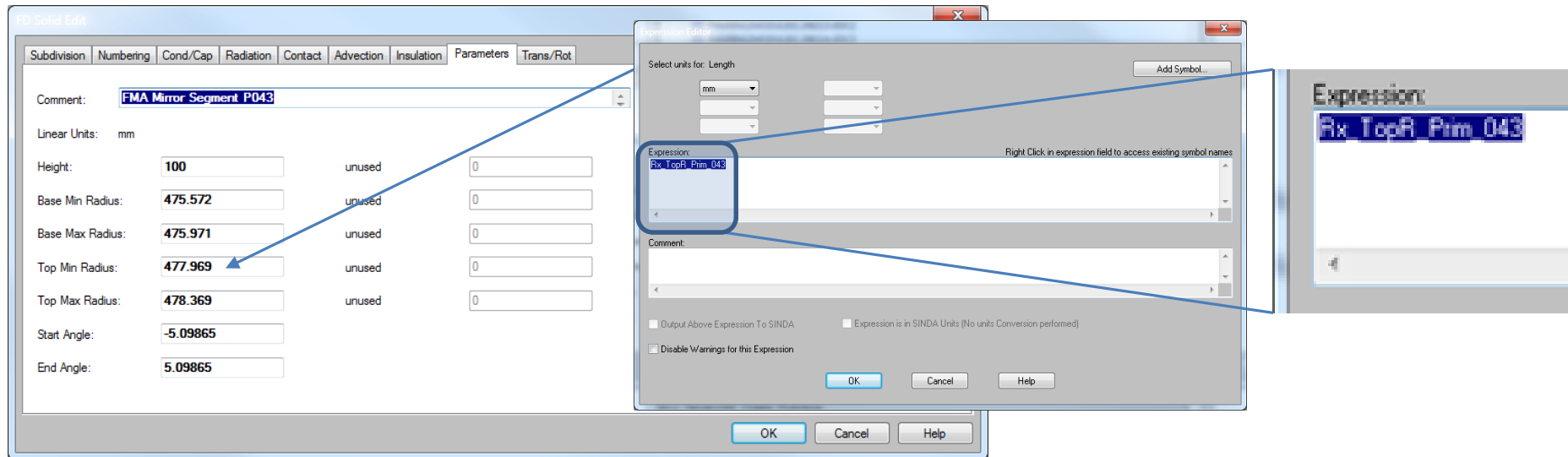
Ready

75%

Topic 1: Building Mirror Segments, Edit Symbol Names in TD Objects



- Step #2a: Create 135 blank TD Solid Cones. Use Multiple Edit Mode to populate all with default symbols and name (suffix “_P000”) . Also populate common inputs (subdivisions, optical and thermophysical properties, radiation active sides).
- Step #2b: Edit each only to update the following.
 - Increment suffix of symbols and name in 9 locations to *_Pnnn*, nnn is shell ID.
 - Input Node Numbering Start ID as *1nnn01* (leading 1 or 2 signifies P versus S).
- Step #2c: Repeat Steps #2a and #2b for 135 Secondary Mirror Segments.

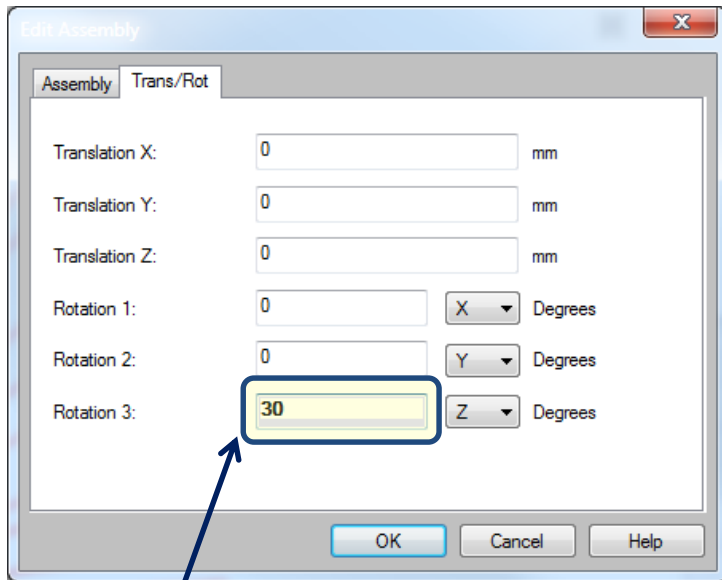


The screenshot displays the 'TD Solid Edit' dialog box with the 'Parameters' tab selected. The 'Comment' field contains 'FMA Mirror Segment P043'. The 'Linear Units' are set to 'mm'. The 'Height' is 100, 'Base Min Radius' is 475.572, 'Base Max Radius' is 475.971, 'Top Min Radius' is 477.969, and 'Top Max Radius' is 478.369. The 'Start Angle' is -5.09865 and the 'End Angle' is 5.09865. The 'Expression Editor' is open, showing the expression 'Rx_TopR_Prim_043'. A callout box highlights the expression field, showing the full expression 'Rx_TopR_Prim_043'.

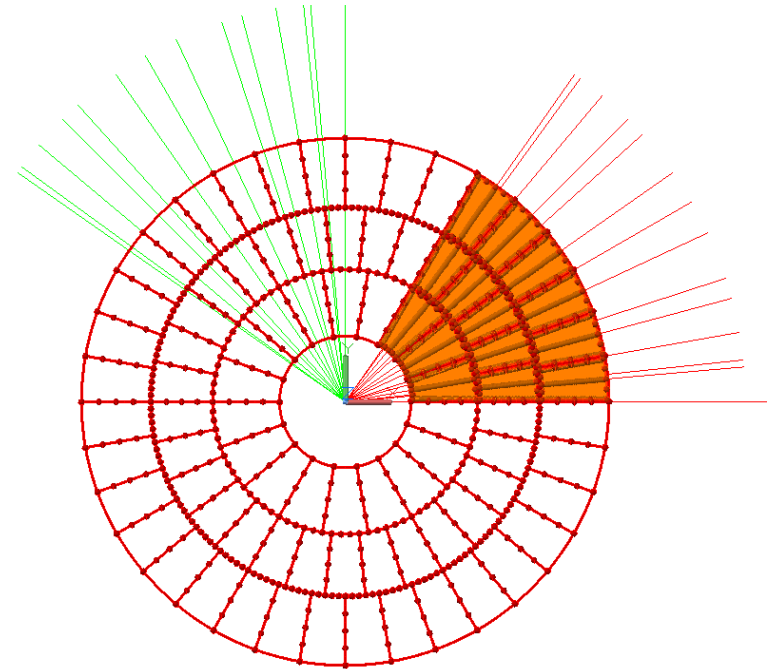
Topic 1: Building Mirror Segments, Duplicate and Rotate Modules



- Step #3a: Create a TD Assembly and a SINDA submodel for each module in each ring.
- Step #3b: Copy modules, attach to TD Assembly, and rotate in place.
- **Step #3c: Using Multiple Edit Mode, assign each complete module to independent SINDA submodel to prevent duplicate node numbers without requiring renumbering of nodes.**



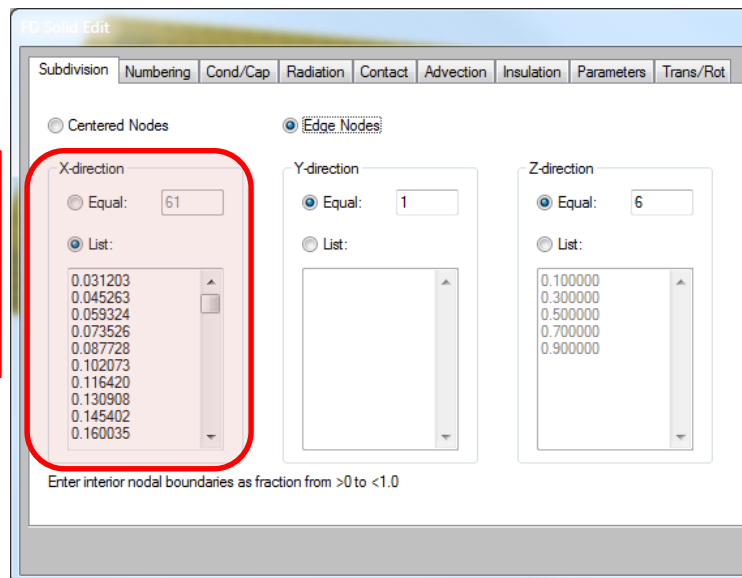
Symbol Also Used for Assembly Rotations



Topic 2: Develop Tool To Calculate Large Nodal Boundary Lists



- Creating Stray-Light Baffles From Separate Finite-Difference Objects Using Edge Nodes Requires Merging As Many As 59 Vanes (TD Solid Cones/Cylinders) To Radial Sides (TD Solid Bricks).
- Issue: Calculate Large Subdivision Nodal Boundary List.
- **Solution: Develop Excel Tool To Calculate Nodal Boundary Lists Given Node Location Inputs (Shown Using Edge Nodes)**



FD Solid Edit

Subdivision Numbering Cond./Cap Radiation Contact Advection Insulation Parameters Trans/Rot

☐ Centered Nodes ☒ Edge Nodes

X-direction

☐ Equal: 61

☒ List:

- 0.031203
- 0.045263
- 0.059324
- 0.073526
- 0.087728
- 0.102073
- 0.116420
- 0.130908
- 0.145402
- 0.160035

Y-direction

☒ Equal: 1

☐ List:

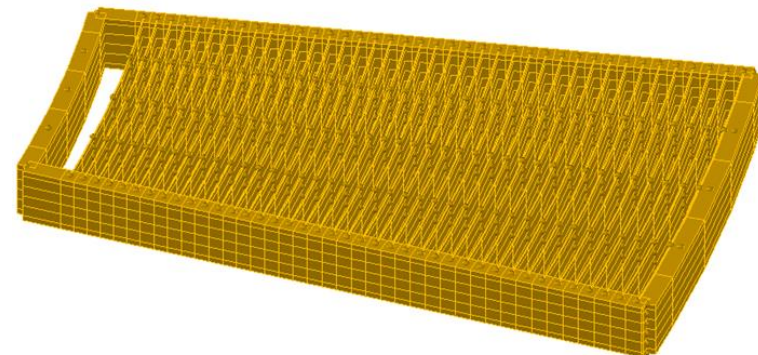
Z-direction

☒ Equal: 6

☐ List:

- 0.100000
- 0.300000
- 0.500000
- 0.700000
- 0.900000

Enter interior nodal boundaries as fraction from >0 to <1.0



**Ring 1 Stray-Light
Baffles Require 60
Nodal Boundaries
in List**

Topic 2: Nodal Boundary List Tool, Problem Statement



- Thermal Desktop Places Nodes at Mid-Point of Each Pair of Interior Boundaries (plus at the edges of the object when using edge nodes).
- Inputs: Node Locations along One Dimension of a Thermal Desktop Finite-Difference Object.
- Outputs/Unknowns: Non-Dimensional Nodal Boundary Locations.
- Matrix Formulation
 - N = total number of nodes (including the edge nodes)
 - A = column vector of inputs, $N - 2$ non-dimensional node locations
 - X = column vector of unknowns, $N - 1$ non-dimensional boundary locations
 - Matrix is simple and sparse with $N - 2$ rows x $N - 1$ columns

$$\begin{bmatrix} 0.5 & 0.5 & 0 & \dots & 0 \\ \vdots & \ddots & \vdots & & \\ 0 & \dots & 0 & 0.5 & 0.5 \end{bmatrix} X = A$$

Topic 2: Nodal Boundary List Tool, Refined Problem Statement



- One Additional Input Required To Make Problem Determinate. Must Specify One Non-Dimensional Nodal Boundary Location.
- Solve By Gaussian Elimination
 - Caution: Although Unique Algebraic Solution Always Exists, Not All Sets of Node Location Inputs Yield Physically Valid Solution.
 - Validity Check: If Resulting Nodal Boundary List is Monotonic, Solution Is Physically Valid.

$$x_i = 2a_{i+1} - x_{(i+1)} = a_{i+1} - (x_{(i+1)} - a_{i+1}) \text{ for } i < k$$

$$x_i = 2a_i - x_{(i-1)} = a_i + (a_i - x_{(i-1)}) \text{ for } i > k$$

Topic 2: Nodal Boundary List Tool, Excel Tool



- Tool Builds by VBA Macro for Specified Number of Edge Nodes.
- Tool Runs with Excel Formulas and Conditional Formatting. Can be Cut and Pasted.
- Includes Prompts and Validity Checks.
 - Relative Gap Between Nodes. (Typically Specify Boundary in Smallest Gap.)
 - Position of Solved Boundaries in Node Gaps. (Indicates Quality of Solution.)
 - Complete and Valid Solutions Output In Column on Right for Easy Cut and Paste into Thermal Desktop.
- Tool Allows for Edge or Centered Nodes and Boundaries Location Inputs substituting for some Node Location Inputs

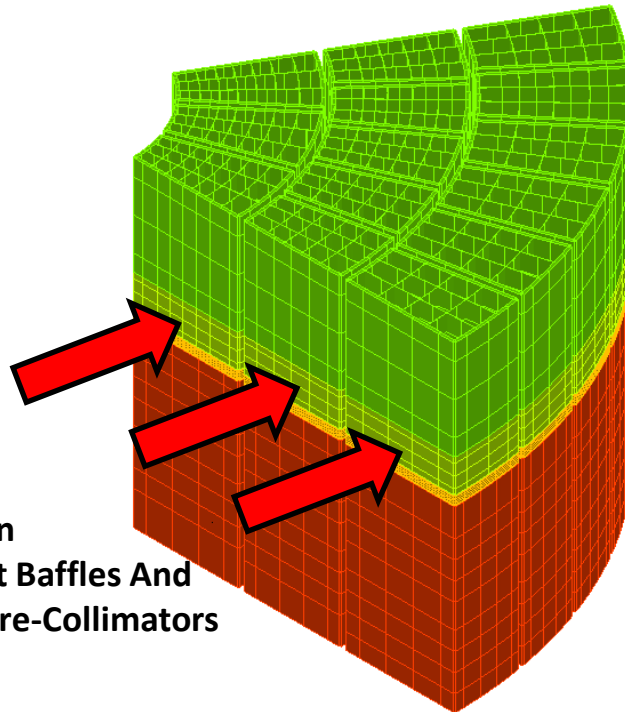
Ring 3 Pre-Collimators: Local Information	Input Node Locations			Specified Boundary			Gaps: Min to Max		Solution (Non-Dimensional)				Check Node Locations			Cut-And-Paste-Ready Result	
	Node #	[mm]	Non-Dim.	[mm]	Non-Dim.	Valid	[mm]	Non-Dim.	Nodes	Bndries	% of Gap	Valid	Node #	Non-Dim.	Match	Bndry List	Non-Dim.
PCL_Ring3InnerHoopRatCL	1	491.2996	0				44.46025	0.274201	0	0.160885	59%	TRUE	1	0	TRUE	0.160885	
PCL_Ring3HoopVane1RatCL	2	535.7598	0.274201				36.7474	0.226634	0.274201	0.387518	50%	TRUE	2	0.274201	TRUE	0.387518	
PCL_Ring3HoopVane2RatCL	3	572.5072	0.500835	554.1335	0.387518	TRUE	38.4361	0.237048	0.500835	0.614152	48%	TRUE	3	0.500835	TRUE	0.614152	
PCL_Ring3HoopVane3RatCL	4	610.9433	0.737883				42.5008	0.262117	0.737883	0.861615	47%	TRUE	4	0.737883	TRUE	0.861615	
PCL_Ring3OuterHoopRatCL	5	653.4443	1						1				5	1	TRUE		

Topic 3: Optimal Set Point Temperatures For Heaters

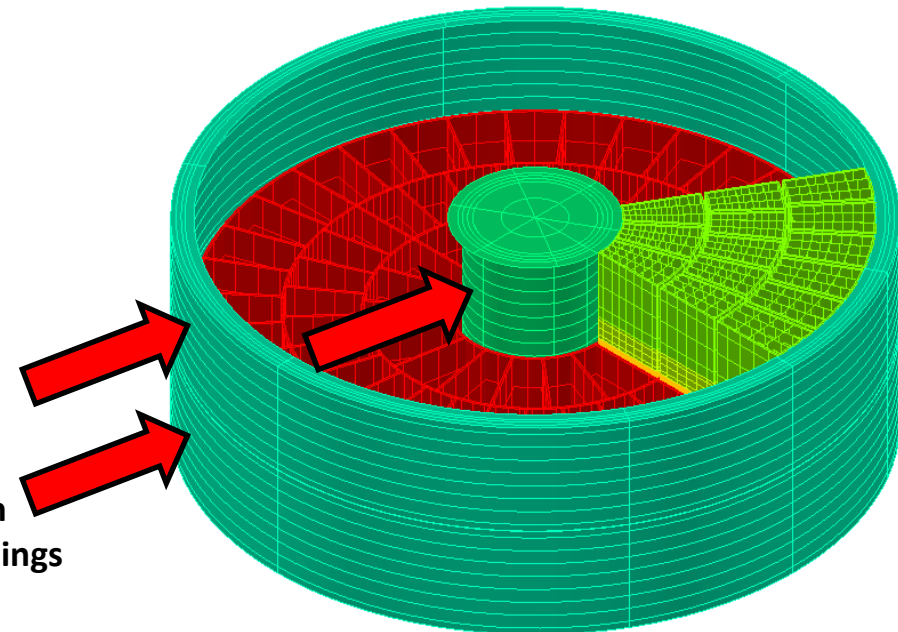


- Mirror Assembly Temperature Controlled By Heaters on Stray-Light Baffles, Thermal Pre-Collimators, and Interface Rings.
- Issue: Determine Optimal Set Point Temperatures For Heaters.
- **Solution: Use SINDA Solver.**

Because Geometry Or Radiation Exchange Factors Unchanged, Dynamic SINDA Not Required.



Heaters On
Stray-Light Baffles And
Thermal Pre-Collimators

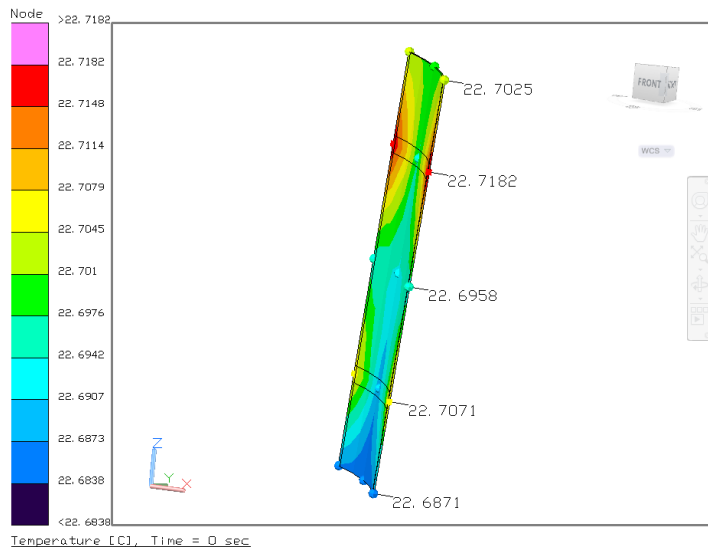


Heaters On
Interface Rings

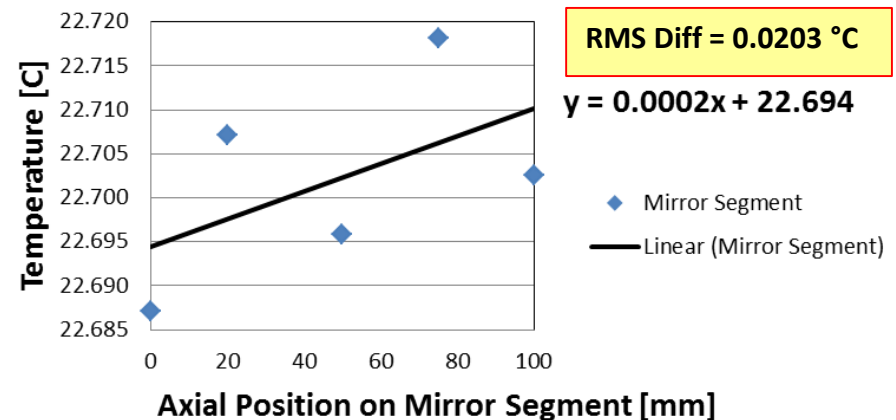
Topic 3: Optimal Set Point Temperatures, Objective Function



- Developed Logic Object Calculating Various Statistics
 - First Order Statistics: e.g. Temperature Range, Temperature Average
 - Second Order Statistics: e.g. Temperature Variance
- Report Various Measures of Merit. Pick One as the Solver Objective Function.
 - Max Value of Statistic in any Segment, Pair, Shell, Module, or Ring and in Mirror Segment Overall
 - Max RMS Value of Statistic over all Segments, Pairs, Shells, Modules, or Rings and over Mirror Segment Overall
- Most Indicative of STOP Analysis: Second Order Statistic of RMS Difference From Least Squares Fit Of Axial Temperature Profile in Mirror Segment Pair, Reported as RMS Over All Pairs



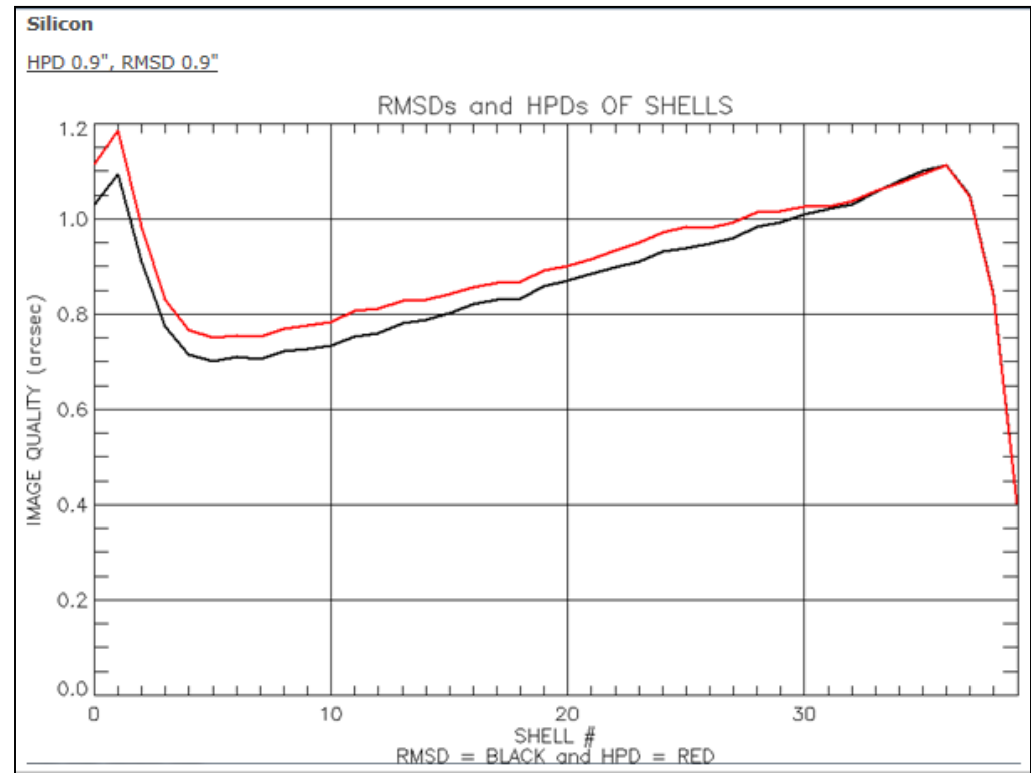
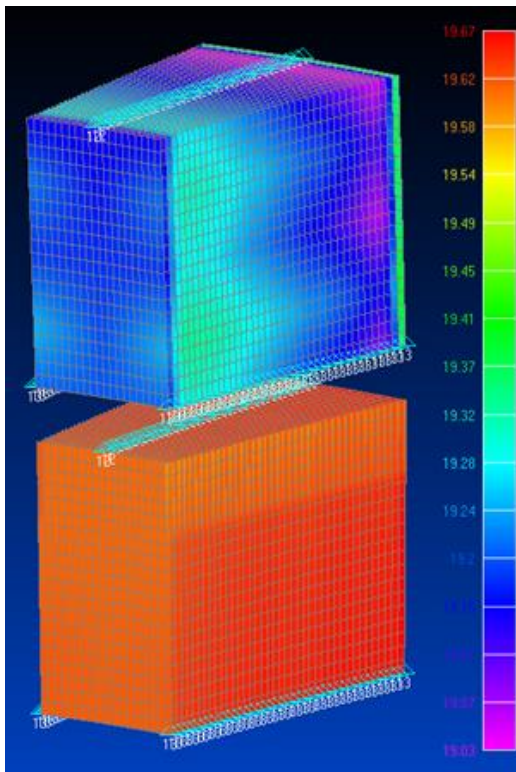
RMS Difference From Least Squares Fit



Conclusion: Initial STOP Analysis Results



- Initial Results From STOP Analysis Using Optimization of Heater Set Point Temperatures Is Encouraging: HPD of 0.9 arc-seconds From Representative Module in Middle Ring





BACK UP



Additional Material

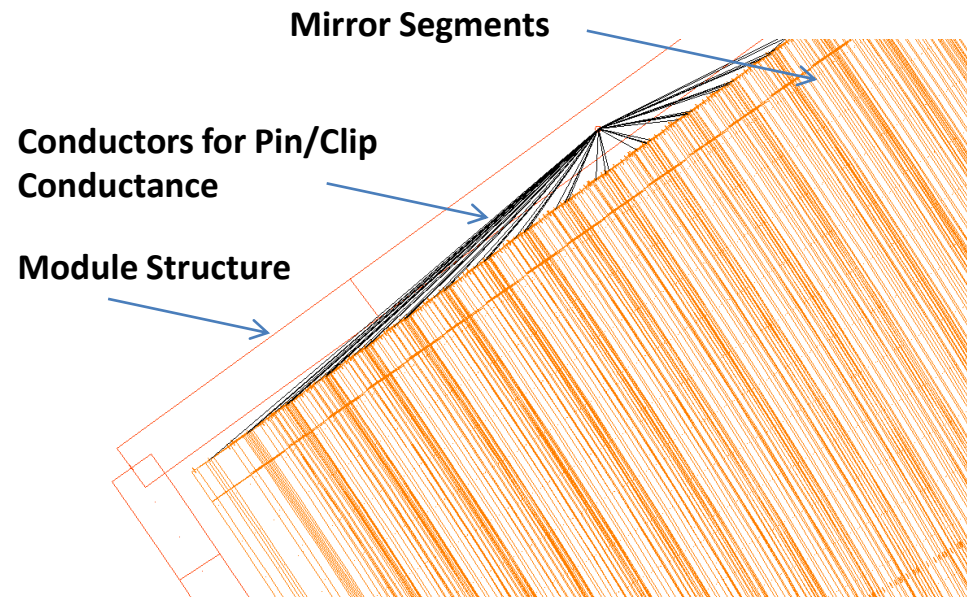
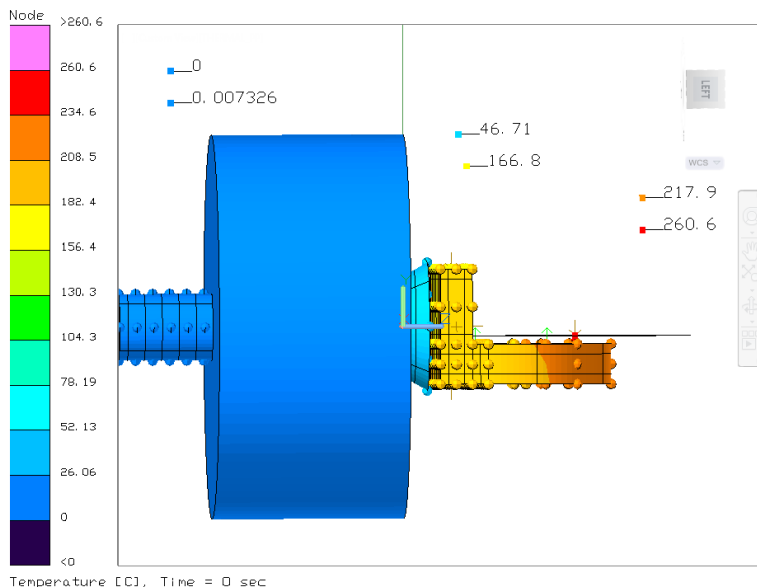
Topic #1

Topic 1: Building Mirror Segments, Build One Module Per Ring



- Step A: Complete one module per ring by adding module structure and conductors modeling pin connections.
- Step B: Add unique Subdivision Boundary Lists to each mirror segment, creating small nodal regions for each pin contact. (Also redefined small nodes as zero mass “arithmetic nodes” and used unique Density Factor for each mirror segment to equate mass.)

Separate Model Calculating Effective Conductance Between Module and Mirror Segments via Pin/Clip





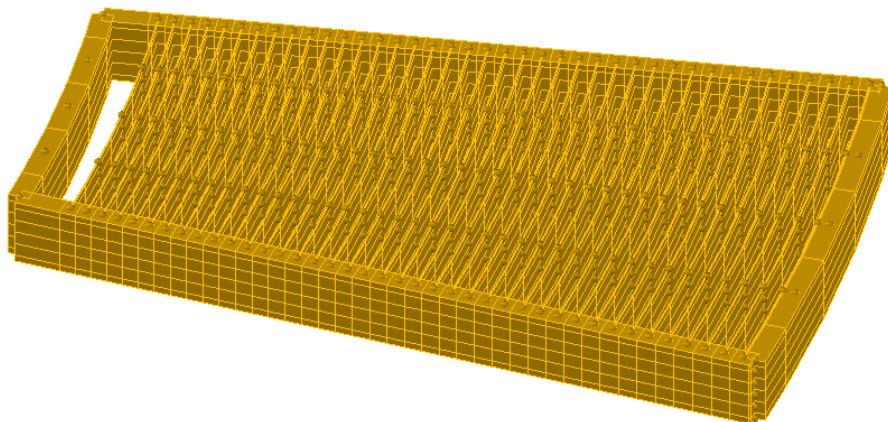
Additional Material

Topic #2

Topic 2: Building Stray-Light Baffles As Merged Finite-Difference Solids



- Step #0: Reuse Existing Module Structure and Mirror Segments.
- Step #1: Create New Symbols with Different Prefix (Change “Rx_” to “SLB_”)
 - Set Base Radii to Top Radii (Baffle Vanes are Cylinders rather than Cones)
 - Geometry Changes: Extend Azimuthal Angles To Center of Structure, Etc.
- Step #2: Copy DWG File. Highlight All “Rx_” Symbols in Symbol Manager, and Select **Rename**. Replace Prefix “Rx_” with “SLB_”. This Changes Symbol Names In TD Objects.
- Step #3: Import “SLB_” Symbols. Geometry updates to Stray Light Baffle.
- Step #4: Use BLOCK to Copy Stray-Light Baffles into Model DWG File.
- **Step #5: Update Subdivision Nodal Boundary List in Structure Sides and Merge Nodes.**



Multi-String Rename Form:

Multiple Rename

☐ Prepend String to each existing name

Prepend string:

☐ Append String to each existing name

Append string:

☒ Replace String

Existing string:

Replacement string:

OK Cancel

Topic 2: Nodal Boundary List Tool, Refined Problem Statement



- One Additional Input Required To Make Problem Determinate. Must Specify One Non-Dimensional Nodal Boundary Location.
- Subscript Key
 - N = total number of nodes
 - a_i = elements of vector A , with i from 2 to $N - 1$
 - x_i = elements of vector X , with i from 1 to $(N-1)$ (where $x_i < a_{i+1} < x_{i+1}$)
 - x_k = single, specified non-dimensional boundary location

$$\begin{bmatrix} 0.5 & 0.5 & 0 & \cdots & 0 & 0.0 \\ \vdots & & \ddots & & \vdots & \\ 0.0 & 0.0 & 0 & \cdots & 0 & 0.5 \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_{(k-1)} \end{bmatrix} + \begin{bmatrix} 0 \\ \vdots \\ 0.5x_k \end{bmatrix} = \begin{bmatrix} a_2 \\ \vdots \\ a_k \end{bmatrix}$$

$$\begin{bmatrix} 0.5 & 0 & \cdots & 0 & 0.0 & 0.0 \\ \vdots & & \ddots & & \vdots & \\ 0.0 & 0 & \cdots & 0 & 0.5 & 0.5 \end{bmatrix} \begin{bmatrix} x_{(k+1)} \\ \vdots \\ x_{(N-1)} \end{bmatrix} + \begin{bmatrix} 0.5x_k \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} a_{k+1} \\ \vdots \\ a_{N-1} \end{bmatrix}$$

Topic 2: Nodal Boundary List Tool, Algebraic Solution



- Solve By Gaussian Elimination
- Caution: Unique Algebraic Solution Exists for Any Set Of Node Location Inputs. However, Not All Sets of Node Location Inputs Provide A Physically Valid Solution.
- Validity Check: Solution Is Valid If Resulting Nodal Boundary List is Monotonic.

$$x_i = 2a_{i+1} - x_{(i+1)} = a_{i+1} - (x_{(i+1)} - a_{i+1}) \text{ for } i < k$$

$$x_i = 2a_i - x_{(i-1)} = a_i + (a_i - x_{(i-1)}) \text{ for } i > k$$



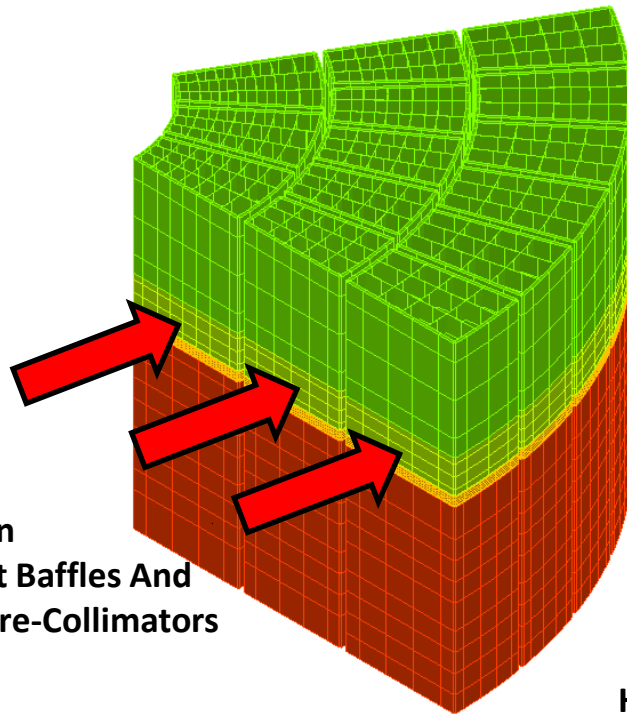
Additional Material

Topic #3

Topic 3: Optimal Temperature Control of Mirror Assembly

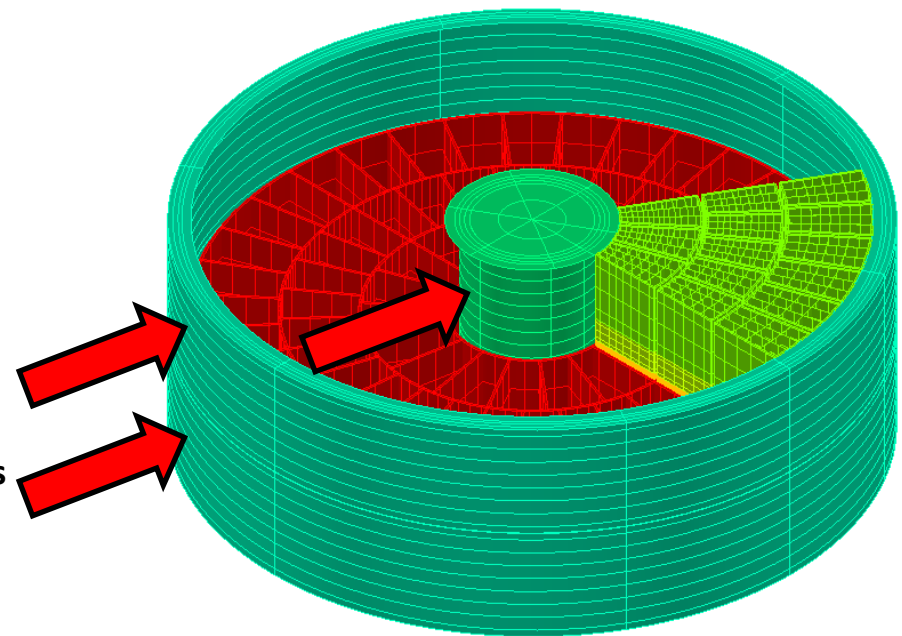


- Mirror Assembly Temperature Controlled By Heaters on Stray-Light Baffles, Thermal Pre-Collimators, and the Interface Rings at the Mirror Assembly ID and OD



Heaters On
Stray-Light Baffles And
Thermal Pre-Collimators

Heaters On
Interface Rings



Topic 3: Optimal Set Point Temperatures For Heaters



- Radiant Heating from Temperature Controlled Stray-Light Baffles, Thermal Pre-Collimators, and Interface Rings Can Offset Heat Loss To Space And Control Mirror Assembly Temperature.
- However, Optimal Heater Set Point Temperatures Not Obvious.
- Issue: Determine Optimal Set Point Temperatures For Heaters.
- **Solution: Use SINDA Solver.**

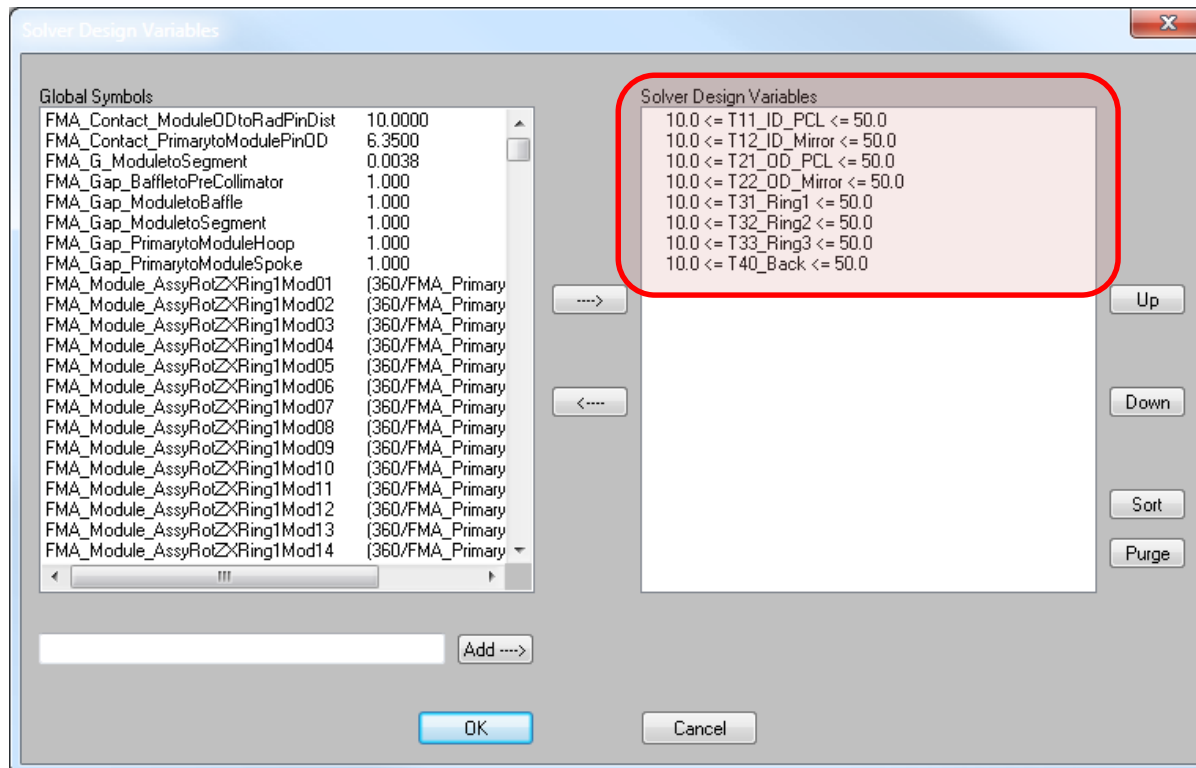
Because Changing Set Point Temperatures Does Not Change Geometry Or Radiation Exchange Factors, Dynamic SINDA Calls To Thermal Desktop Are Not Required.

The Solver Can Efficiently Run Many Steady-State Solutions, Even For This Large Geometry.

Topic 3: Optimal Set Point Temperatures, Design Variables



- Define TD Symbols/SINDA Registers For Each Set Point
- Constrain Set Points Between 10 °C – 50 °C.



Topic 3: Optimal Set Point Temperatures, Average Temperature Constraint



- Desire Solution Providing Average Mirror Segment Temperature of 20 °C.
- Solver Struggled With This Tight Restraint. Solution Involved OPERATIONS Logic And Two Calls To Solver.
 - 1st Solver Call: Loosely Constrain Average Temperature Between 19.5 °C – 20.5 °C
 - Interim Logic: Adjust All Set Points To Equating Average Temperature To 20 °C
 - 2nd Solver Call: Re-Optimize With Tight Constraint of 20 °C In Vicinity Of 1st Solution

